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Classical Dynamics - DAMTP

Appraisal of a Cambridge lecturer in classical mechanics, circa 1690 11 Introduction The fundamental principles of classical mechanics were laid down by Galileo and New-ton in the 16 thand 17 centuries In 1686, Newton wrote the Principia where he gave us three laws of motion, one law of gravity and pretended he didn't know cal-culus

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PHYS 705: Classical Mechanics

Example: Harmonic Oscillator cos sin (*) gP pgP X x X m With the form of H as sums of squares , we will try to exploit 1 2222 2 Hpmx m Let try X is cyclic in K! sin cos 122 Substituting these into our Hamiltonian, we have

Phys 4001 Classical Mechanics Fall 2011

parable to the chosen text Some are older standards, others more recent These include Mechanics by Symon, Classical Dynamics of Particles and Systems by Thornton and Marion, or (Marion and Thornton, or just Marion, depending on edition), Classical Mechanics by Chow, and Introduction to Classical Mechanics by Arya

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Solutions - CERN

Solutions 171 The trajectory drawn with an angle of fJ = 45 degrees (lz'l = 1) and a tacking fJ - + -fJ at x = L/2 has a total length LV2 and a velocity greater than (wO -wl)/2The time along this path, Tv = 2LV2/(wO - wI), is obviously shorter than the time along the path with no tacking, Tv = 2L(zl/L)/(wO - wI) = 2zl/(wO - wI) In realistic cases, for instance the America's Cup, one can see how

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